

### Product description • Functional description • Performance features

### **Product description**

Microprocessor based system for control and monitoring of fume hood exhaust air volume flow or face velocity in relation to the front sash and slide window opening. Depending on the configuration the following operating modes for fume hood control are possible:

#### Standard model

face velocity control	iCM-F
with optional add on system -E2	
<ul> <li>face velocity control with</li> </ul>	iCM-FP
limitation to V <sub>MIN</sub> and V <sub>MAX</sub>	
<ul> <li>position sensor control</li> </ul>	iCM-W
<ul> <li>fully variable control</li> </ul>	iCM-V

• constant control (1, 2 or 3 point) iCM-K

The integrated functional monitoring in accordance with **EN 14175** offers maximum safety for laboratory staff. When the exhaust air setpoint that is to be regulated is underrun, an acoustic and optical alarm is activated.

Suitable for all fume hood constructions and extraction units. Standard model with air flow sensor.

### **Functional description**

In order to calculate the exhaust air volume flow that is to be regulated, the vertical (sash position sensor) and horizontal (air flow sensor) adjustment of the sash opening is determined. The calculated sash opening serves as a command variable and setpoint value for the air volume flow that is to be regulated. A high-speed control algorithm constantly compares the setpoint with the actual value measured by a air flow sensor and regulates the constant face velocity (air input speed) quickly, precisely and steadily, independent of pressure fluctuations in the duct system. The precalculated exhaust air requirement developed by SCHNEIDER is calculated immediately and is available as a setpoint. This considerably improves the control time of the room air controller (e.g. SCHNEIDER VAV supply air volume flow controller).

### Advantages of the sash dependent variable fume hood controller

The containment-safety of the fume hood is guaranteed in all sash opening positions while at the same time ensuring minimal air consumption. Ventilatory robustness of fume hood operation is achieved by appropriate programming of the constant face velocity and can be individually adapted to any type of fume hood construction. The air flow sensor is used in the standard model. The optional add-on system -E2 allows the connection of three independent sensors (sash position sensor, static differential pressure transmitter and air flow sensor). The controller iCM checks these three sensors for mutual plausibility. The logical context of the actual values of the differential pressure and air flow sensors in relation to the actual value of the sash is constantly checked and validated. This represents a considerable increase in the safety potential for the entire control system and for the user. Measurement errors and discrepancies are recognized and signalled immediately.



### **Performance features**

### Standard model

- Microprocessor based variable control system with full graphic LC display
- Numerical and bar graph display of the air input velocity in m/s or ft/min
- Compact low cost built in system
- External plug in adaptor 230V AC/15V DC
- All system data are saved mains voltage failure-safe in the EEPROM
- Programming and read out of all system values via the service module SVM100 or software PC2500
- Air flow sensor for measuring the face velocity
- Air volume flow range 10:1
- Integrated functional monitoring of fume hood operation in accordance with EN 14175 with acoustic and optical alarm
- Optical and optionally acoustic alarm for the operating status "Sash position > 50cm"
- Emergency operation (override) = VoverRide
- Night-time operation (reduced operation) = VNIGHT
- Monitoring of supply air and exhaust air systems
- High-speed, predictive control algorithm
- Rapid, stable, precise control through direct activation of the servo motor with feedback potentiometer
- Reaction time and upward regulation of the exhaust air volume flow ≤ 2 sec (V<sub>MIN</sub> → V<sub>MAX</sub>)
- Programming of the downward regulation control time for the exhaust air volume flow ≤ 2...24 sec (V<sub>MAX</sub> → V<sub>MIN</sub>)
- Closed loop control

### with optional add on system -E2

- Integrated power supply 230V AC
- Separate terminal board for for simple cable connection and fast commissioning
- Static differential pressure transmitter 3...300 pa (optionally 8...800 pa) with high long-term stability for measuring the exhaust air actual value (volume flow)
- Maintenance-free measuring tube with two ring chambers and self-cleaning effect
- Linear sash position sensor for stable, error-free measurement of the vertical front sash opening
- Internal functional monitoring of all sensors for plausibility
- Suitable for all fume hood constructions

### **Functional description**

### **Building management system**

The building management system (BMS) balances the ventilation requirements of the entire building and can also check all room controllers for plausibility. Daytime/nighttime operation, visualization of malfunction notifications and actual values as well as remote maintenance and error diagnostics can easily be integrated. Determination of room-related air consumption and individual billing is also possible.

### Function display and control panel with fully graphic and numerical LC-Display

The function and control panel is available as a build in version with fully graphic LC-Display.

#### **Functions:**

- Acoustic and optical alarm (red LED) for insufficient exhaust/supply air
- Optical display (green LED) for sufficient exhaust/ supply air
- н. Numerical and bargraph display of the air input speed (face velocity) in m/s or ft/min.
- Yellow blinking LED as an optical warning signal for the operating status "Sash position > 50cm"
- RESET button for acknowledgement of the acoustic alarm
- Button Control ON/OFF
- н. Button Light ON/OFF (fume hood interior lighting)
- н. Button V<sub>MAX</sub> with LED status display for emergency operation (override)
- Button Set with LED status display for night-time reduction (reduced operation)
- Integrated user operating interface for programming
- Plug for programming via the service module SVM100 or laptop (program PC2500)

#### Schematic diagram: Fume hood controller iCM

### Fume hood controller operating modes

Depending on the configuration and the area of application, various modes of operation are possible. The following control types are implemented:

#### Standard model

- face velocity control iCM-F with optional add on system -E2 face velocity control iCM-FP
- with limitation to  $V_{MIN}$  and  $V_{MAX}$ sash position control iCM-W
- fully variable control iCM-V
- constant control (1 point) iCM-K

Damper actuator with feed back potentiometer Damper Air intake speed sensor PLUG IN POWER SUPPLY 230V AC/15V DC Fume hood Controller iCM 15V D0 0,3 m/s Day/night operation/On-Off Analogue output **ė :** Relay output Monitoring acc. to EN 14175

Technical documentation iCM • Date: 05/2013 • www.schneider-elektronik.com

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#### **Operating modes**

### Standard operating mode iCM-F Constant face velocity

The operating mode **iCM-F** (standard mode) or **iCM-FP 8only with add on system -E2**) regulates at a constant face velocity (e.g. v = 0,3...0,5 m/s), independent of the sash position. The exhaust air volume flow is changed in relation to the fume hood sash position so that the face velocity remains constant. The fume hood exhaust air volume flow is regulated either by a motor-driven damper (in hoods connected to a central exhaust air system) or by an integrated exhaust air motor with a frequency inverter.

Pressure fluctuations in the duct system are regulated quickly, precisely and steadily. The face velocity v and additional with FC500-FP the exhaust air volume flows V<sub>MIN</sub> und V<sub>MAX</sub> are freely programmable.

### Air volume limitation $V_{\text{MIN}}$ und $V_{\text{MAX}}$ (operating mode iCM-FP only with optional add on system -E2)

When the sash is closed, the face velocity is increased v > 0,3 m/sec. To ensure the security of the laboratory staff, a minimum exhaust air volume flow  $V_{\text{MIN}}$  is guaranteed. Regulation now takes place to a constant minimum exhaust air volume flow.

When the sash is opened, the face velocity is reduced v < 0,3 m/sec. When the safe exhaust air volume flow  $V_{MAX}$  for the specific fume hood is reached, this value is constantly regulated. Thus the fume hood is within the safe range and definitely containment-safe. The restriction of the exhaust air volume flow to  $V_{MAX}$  ensures an energy saving effect and guarantees maximum safety for the laboratory staff. The load on the ventilation system is only as high as is absolutely necessary for the operating status of the particular fume hood.

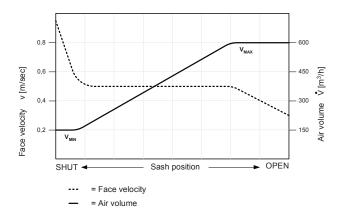


Figure 1: face velocity control

### Air flow sensor

With the air flow sensor developed by SCHNEIDER a change in position of the sash and/or slide window is automatically detected and integrated in the control algorithm.

### Sash position dependent control (operating mode iCM-W only with optional add on system -E2)

In fume hoods without a slide window, only one sash position sensor is needed to for exact measurement of the vertical sash position.

The specification of setpoints by the sash position sensor enables stable, fast and accurate control. If turbulent and indefinable air flows are present in the laboratory that may affect the measuring accuracy and stability of the air flow sensor, a sash position sensor **SPS-100** is always a better choice than a flow sensor **AFS-100**.

The sash position measured by the sash position sensor is the setpoint for the **iCM-W** controller, which calculates the required exhaust air volume flow and and regulates it as needed. Volume flow is always linear in relation to the position sensor.

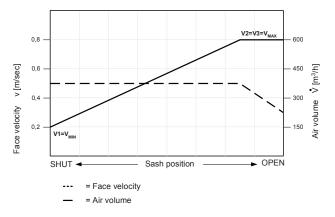


Figure 2: Linear sash position control

### Operating modes

### Fully variable volume flow control (operating mode iCM-V only with optional add on system -E2)

In terms of energy efficiency, this mode of operation is the most expedient and the best method of fume hood control. A very fast and yet stable control algorithm is the most notable technical feature of this control mode.

The operating mode **iCM-V** (only with optional add on **system -E2**) seamlessly regulates the exhaust air volume flow in relation to the fume hood sash position. The fume hood exhaust air flow is regulated either by a motor-driven damper (in hoods that are connected to a manifold air system) or by an integrated exhaust air motor with a frequency inverter.

Pressure fluctuations in the duct system are regulated quickly, precisely and steadily. The exhaust air volume flows V1, V2 and V3 are freely programmable and define the vertices of the control curve.

### $V1 = V_{MIN}$

When the sash is closed (SHUT) regulation takes place according to a programmable V1 exhaust air flow (minimum exhaust air flow). The containment-safety of the fume hood is guaranteed at all times while air consumption remains at a minimum.

### V2 = V<sub>50cm</sub>

The second vertex of the volume air flow is V2, which represents the exhaust air volume flow when the sash is partly open (e.g. sash = 50 cm). Seamless regulation of the required exhaust air volume flow takes place independent of the sash opening between V1 and V2 (SHUT  $\leq$  sash  $\leq$  50 cm). The vertices V1, V2 and V3 are freely programmable and can be assigned to any sash opening, e.g. V2 at sash = 50 cm.

### $V3 = V_{MAX}$

The third vertex of the exhaust air volume flow is V3, which represents the exhaust air volume flow when the sash is fully open (e.g. sash = 90 cm). Seamless regulation of the required exhaust air volume flow takes place between V2 and V3 (50 cm  $\leq$  sash  $\leq$  90 cm) and is dependent on the sash opening.

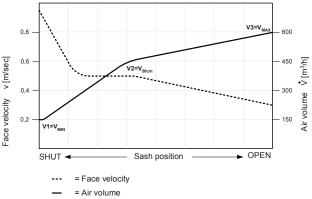


Figure 3: Fully variable control

### **Constant 1 setpoint controllers**

### (operating mode iCM-K only with optional add on system -E2)

The operating mode **iCM-K** (only with optional add on **system -E2**) regulates the exhaust air volume flow in relation to the sash position of the fume hood. The fume hood exhaust air is regulated either by a motor-driven damper (for hoods that are connected to a central exhaust air system) or by an integrated exhaust air motor with a frequency inverter.

Pressure fluctuations in the duct system are regulated quickly, precisely and steadily. The exhaust air volume flows V1 is freely programmable.

### 1 point constant controllers

In 1 point constant controllers the exhaust air volume flow is constantly regulated at V1, independent of the sash position.

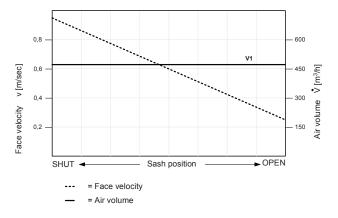


Figure 4: 3 point constant control

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#### Air flow sensor and actor

### Dynamic air flow sensor (standard mode)

Using a air flow sensor developed by SCHNEIDER a change in position of both the slide window (horizontal) and the front sash (vertical) is registered on the fume hood and provided as a standardized output signal 0...5 V DC.

A measuring principle devised by SCHNEIDER recognizes the direction of the air flow and enables very precise, fast measurements in the range 0...1 m/s. This measuring range is particularly suitable for determining the face velocity speed in fume hoods (e.g. 0,3..0,5 m/s).

The air flow sensor **AFS100** is mounted on the fume hood in a suitable position and measures the flow of air in the bypass into the fume hood.

The air flow measured in the bypass corresponds exactly to the face velocity in the sash area, both in the open and shut positions. If the sash is opened, the face velocity drops and is thus directly dependent on the sash opening. The face velocity (e.g. 0,3...0,5 m/s) is regulated stable within < 2 s.



# potentiometer (standard mode)The required exhaust air volume flow is adjusted via the

Damper with fast servo motor with feedback

damper. The very fast servo motor (3 s running time for 90 °) specially developed for SCHNEIDER is mounted directly on the damper shaft and has a torque of 3 Nm. The servo motor is operated directly by the control electronics (Fast Direct Drive), which guarantees fast, stable control behaviour. This operating mode has considerable advantages over analogue motor operation (0...10V DC), because the internal control electronics of the analogue (continuously) controlled servo motor have a hysterisis which can lead to control fluctuations if the volume flow differences that are to be regulated are small.

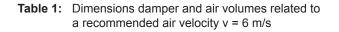
A feedback potentiometer reports the actual value of the current damper position to the control electronics. A special control algorithm quickly and directly "starts up" the required exhaust air volume flow without undefined overshoot.

When the servo motor is activated, a damper control concurrently checks whether the damper position is actually changed. This control concept with integrated servo motor monitoring functionality exceeds the stringent safety criteria for fume hood controllers.

In standard mode iCM-F (constant face velocity) the damper comes without integrated venturi measuring tube. The limit positions of the damper (damper SHUT=0% and damper OPEN=100%) can be freely programmed. The servo motor stops automatically at the programmed limit damper position and controls only within the programmed bandwidth (e.g. between 10...80%).

Figure 5: Air flow sensor

Nominal diameter DN [mm]	Overall length L [mm]	Volume flow V <sub>MAX</sub> [m³/h]
160	150	434
200	170	679
250	175	1060
315	175	1683
400	180	2714



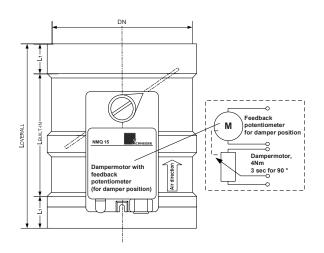


Figure 6: Damper with fast servo motor with feedback potentiometer



### Optional add on system -E2

The optional add-on system -E2 is simply connected to the iCM controller and placed on the roof of the fume hood. It allows the connection of three independent sensors (sash position sensor, static differential pressure transmitter and air flow sensor). In addition to the standard **face velocity controller iCM-F**, the following operating modes can be implemented:

with	optional add on system -E2	
		iCM-FP
	with limitation to $V_{\text{MIN}}$ and $V_{\text{MAX}}$	
	sash position control	iCM-W
	fully variable control	iCM-V
	constant control (1 point)	iCM-K

The optional add-on system -E2 includes a static differential pressure transmitter and, together with the damper with integrated venturi measuring tube, the sash dependent exhaust air volume flow (with position sensor) can be regulated as well as the constant face velocity. These extended operating modes ensure more stable and precise control and also enable plausibility checks of the connected sensors.

This is a significant safety improvement for the entire control system and for the user. Measuring errors and differences are recognised and signalled immediately.

Depending on the desired operating mode, the corresponding sensor is connected to the optional add-on device -E2.

The add-on device -E2 also has relays for light (contact load 250V AC/16A), malfunction alarm and On/Off (contact load 250V AC/3A), its own 230V AC/15V DC power pack and galvanically separated BMS inputs via optocoupler for On/ Off and Daytime/Nighttime operation.

### Sash position sensor (only with optional add on system -E2)

undershoot are largely avoided.

A sash position sensor (cable potentiometer) determines the vertical sash position with an absolute accuracy of more than 2 mm (0,2%). The reproducible and seamless linear determination of the sash position enables very fast, precise, stable control. With this technique overshoot or

The sash position sensor is easy to mount and ensures an absolutely safe and stable actual value signal for the vertical sash position.

The sash position sensor cable has an ejection length of 1m and can easily be hooked into the front sash counterweight.

The **SPS100** position sensor developed by SCHNEIDER is specially designed for precise, reproducible determination of the vertical sash opening height.

### Static differential pressure transmitter (only with optional add on system -E2)

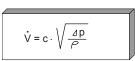
Static differential pressure measurement is suitable for contaminated or abrasive air, because the air does not flow through the static differential pressure transmitter.

### Measuring volume flow with a static differential pressure transmitter

The basis for determining the volume flow is the differential pressure on the damming body, which may take the form of a venturi tube, a measuring orifice or a measuring cross. SCHNEIDER always uses the venturi measuring principle due to its very high measuring accuracy and especially due to the fact that it is not dependent on a inlet and outlet route.

Air flow that occurs on a damming body generates resistance pressure proportional to flow velocity, which results in differential pressure. Measurement over the entire measuring range 3...300 pa (optional 8...800 pa) is very precise and stable, which means that a volume flow range of 10:1 can be regulated.

The volume flow is calculated using the following formula:



 $\dot{V}$  = Air volume c = geometric constant of the measuring system  $\Delta p$  = Differential pressure

 $\rho$  = Density of the air



Figure 7: Linear position sensor for determining the sash position



### Extended operating modes with optional add on system -E2

### Measuring and control components

Accurate design of the measuring and control components is crucial for the speed, stability and accuracy of the entire control process. SCHNEIDER products are developed with the best available technology and fulfill these requirements.

### Maitenance-free measuring tube with integrated damper (only with optional add on system -E2)

SCHNEIDER offers two measuring systems MD (maintenance-free measuring tube) and VD (venturi tube), which has the following advantages:

- Maintenance-free operation due to self-cleaning measuring system
- Very high measuring accuracy (better than 3%)
- Integrated annulus measuring process
- Very good sound levels due to favourable inflow
- Compact design (e.g. DN250, overall length=400mm)
- Independent of the inlet and outlet route

Due to the compact design and the insensitiveness from a inlet route the system can be mounted directly on the fume hood exhaust air outlet.

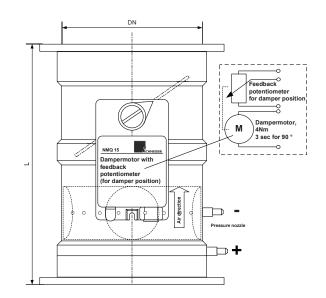


Figure 9: Schematic diagram connection of servo motor with feedback potentiometer

### **Compact design**

In consideration of structural conditions in laboratories, we have developed a compact venturi tube that can be mounted directly on the fume hood exhaust air outlet. A special inlet route is not necessary. For a pipe diameter of DN200 the compact venturi tube with integrated damper requires a length of just 310 mm (optionally 235 mm).

Table 2 shows the relationships between the nominal diameter (DN), overall length (L) and the maximum volume flow  $V_{MAX}$  at a flow velocity of 6 m/s.

Nominal diameter DN [mm]	Overall length L [mm]	Minimum Volume flow V <sub>MIN</sub> [m³/h]	Maximum Volume flow V <sub>MAX</sub> [m³/h] (v = 6m/s)
160	340	59	434
200	350 optionally 235	100	679
250	400	163	1060
315	490	267	1683

 Table 2:
 Nominal diameters of the maintenance-free measuring tube MD with integrated damper



Figure 8: Damper with integrated venturi tube MD and fast servo motor, running time 3 s for 90° Model: flange/flange



### Fast upward regulation and slow downward regulation

In all operating modes regulation is always upwards and at maximum velocity, i.e. when the front sash or slide window is opened, the calculated required volume flow follows and is increased without delay.

When the front sash or slide window is closed, downwards regulation can be done at adjustable speed of 2...24 s. Slow downwards regulation has the advantage that there is sufficient time for the required room supply air and the laboratory always remains in a state of negative presssure in all operating conditions.

Slow downwards regulation of the volume flow increases work safety for the laboaratory staff and eliminates the tendency towards oscillation of the entire control system.

### Plausibility check with three different sensors (only with optional add on system -E2)

The **iCM-V** controller uses **three different sensors** (sash position sensor, static differential pressure transmitter and air flow sensor) to constantly check the mutual plausibility of the sensors, i.e. it is checked whether the actual values of the sensors (differential pressure transmitter and air flow sensor) are logically in line with the sash position sensor setpoint. This offers additional security for the entire control system and for the user.

### **Control parameters**

All project-specific control parameters, such as the upper and lower limits for maximum and minimum volume flow, can easily be retrieved, changed and monitored on site via the internal system level or a laptop. Cyclic, sequential retrieval and verification of the control actual and setpoint values guarantees fast, stable, demand-related volume flow control.

### Teach-in mode

A software controlled, automatic self-learning mode (teach in) facilitates and optimizes setup. The **iCM-V** controller determines and programs all necessary system data and control parameters fully automatically in teach in mode.

### Test and diagnostic functions

A comprehensive, accurate overview of the measured actual values is essential for setup, diagnostics and troubleshooting.

With a special test and diagnostics program, SCHNEIDER provides service and setup staff with the following actual values in the service module SVM100 or PC software PC2500.

In addition, an integrated user interface for programming is implemented that can be accessed with the function keys and is password protected.

Actual value	Unit
Exhaust air	m³/h
Supply air	m³/h
Face velocity	m/s
Sash position (with position sensor)	%
Exhaust air pressure (measured by venturi tube)	ра
Damper position	%
Temperature (with PT-1000 measuring element)	°C

### The following tests can be carried out:

### Show digital inputs Shows the current status of all digital inputs

### Analogue inputs

Shows all analogue inputs with the current signal voltages

Analogue outputs

Shows all analogue outputs with the current signal voltages

Motor/damper test

With this test function the motor/damper can be set to OPEN and SHUT

These test and diagnostic functions greatly facilitate and simplify system setup and troubleshooting.



### Controller dimensions and planning values

### Notes on control dimensioning (dimensions and volume flow)

During constant face velocity control, the exhaust air volume flow V is calculated from the inflow area A  $[m^2]$  (open sash or slide window) and the face velocity v using the following formula:

 $V = A \cdot 3600 \cdot v$ 

### Calculation example:

Given that: Fume hood width = 1.2 m Sash opening = 10 cm Face velocity v = 0.3 m/s

V = 1,2 • 0,1 • 3600 • 0,3 V = 129,6 [m<sup>3</sup>/h]

At a sash opening of 10 cm, a sash width of 1.2 m and a face velocity of 0.3 m/s the volume flow is 129.6  $[m^3/h]$ .

The following table shows the resulting volume flow V  $[m^3/h]$  for various inflow areas and a constant face velocity of 0.5 m/s.

At a sash opening width of 1.5 m and an sash opening height of 50 cm the volume flow is V = 1350 [m<sup>3</sup>/h].

Sash opening width [m]	Sash opening hight [cm]	V [m³/h]	Sash opening hight [cm]	V [m³/h]
1,2	5	108	50	1080
1,5	5	135	50	1350
1,8	5	162	50	1620

At a constant face velocity v = 0.3 m/s the volume flows decrease by 40%.

Due to the control accuracy, care must be taken to ensure that at minimum volume flow  $V_{\rm MIN}$  the flow velocity in the fume hood controller does not fall below 1,05 m/s.

Due to noise radiation, in laboratory applications care must be taken to ensure that at maximum volume flow  $V_{MAX}$  the flow velocity in the volume flow controller does not exceed 7,5 m/s.

### VAV dimensions for room application

The volume flows V<sub>MIN</sub>, V<sub>MED</sub> and V<sub>MAX</sub> are freely programmable within the range 50...25.000 m<sup>3</sup>/h, but care must be taken that the dimensions of the VAV for room supply and room exhaust air are appropriate in relation to the volume flow range while at the same time taking the flow velocity into account.

### Determining volume flow for laboratory applications with regard to the flow velocity v

Volume flow	Flow velocity v
V <sub>MIN</sub>	v ≥ 1,05 m/s
V <sub>MAX</sub>	v ≤ 6 m/s

### Planning values for sound and exhaust air volume flow

The tables on pages 14 to 15 should be consulted when planning a system, in order to project an optimal ratio between exhaust air volume flow, control behaviour and minimum sound values.

### Planning values for duct pressure

The duct pressure on the fume hood controller is calculated to the given air volume flow and is the addition of the controller pressure loss ( $\Delta pv$ •factor 3) plus the pressure loss of the connected fume hood (controller pressure loss  $\Delta pv$  see table 5 on page 15).

### Example:

Given:	MD measuring tube DN250 max. air volume flow = 720 m <sup>3</sup> /h fume hood pressure loss acc. to manufacturer e.g. 40 Pa
Calculated:	air velocity = 4,08 m/s
Table 3 :	∆pv = 14 Pa ∆pv•3 = 14•3 = 42 Pa

The multipilcation with factor 3 guarantees a save and stable air volume control over the whole range and a sufficient damperposition

Calculated minimum duct pressure: 42 + 40 = 82 Pa

Choosen minimum duct pressure with controller DN250 and maximum	
with controller DN250 and maximum	
air volume flow = 720 m <sup>3</sup> /h:	ca. 100 Pa



### Ordering code: Fume hood controller

Order code: Fum	e hood	cor	ntroll	er lange stante	
i	CM - F	<b>-</b> ]-[	0	Important: Order the DK damper or the MD measuring tube with damper and actuator additionally.	
Type				Ontional add on avetam with own appa	
Control type		L		Optional add on system with own case	
Face velocity		F ∥	0	no add on system (standard mode)	
Extended operating mode only Please order Round damper DK with a			Please order Round damper DK with actuator additionally		
with optional add on system			E1	Add on system with 3 relays and 2 digital inputs for BMS	
Face velocity with VMN and VM	MAX <b>F</b>	P		Please order Round damper DK with actuator additionally	
limitation			E2	Add on system with 3 relays and 2 digital inputs for BMS and static	
Sash position sensor	V	N	differential pressure transmitter for extended operating/control n Please order Round damper with measuring tube and actu		
Fully variable	1	V			
Constant (1-Punkt)	ł	ĸ		MD or VD additionally	

### Ordering example: Fume hood controller iCM-F-0

Control mode = face velocity, 3 relays, integrated function display with graphic LCD and control panel, with plug-in power supply.

Make: SCHNEIDER

Typ: iCM-F-0

Please order round damper with actuator DK additionally.

### Power supply:

The standard model iCM-F (face velocity) is delivered with a plug-in power supply.

Extended operating mode with optional add on system -E2						
Control type	Sensors included with delivery	Order code for opti- onal add on system	Damper without/with measuring tube			
<b>F</b> = Face velocity	air flow sensor	-0 oder -E1	DK (without measuring tube)			
Extended operating mode only with optional add on system -E2						
<b>FP</b> = Face velocity with $V_{MIN}$ and $V_{MAX}$ limitation	air flow sensor, differential pressure transmitter	-E2	MD or VD (with measuring tube)			
<b>W</b> = Sash position sensor	sash position sensor, diffe- rential pressure transmitter	-E2	MD or VD (with measuring tube)			
V = Fully variable	position sensor, air flow sensor, differential pressure transmitter	-E2	MD or VD (with measuring tube)			
K = Constant (1-Punkt)	differential pressure transmitter	-E2	MD or VD (with measuring tube)			

### Ordering example: Fume hood controller iCM-F-W-E2

Control mode = sash position sensor, integrated function display with graphic LCD and control panel, with optional add on system -E2, 3 relays, static differential pressure sensor and integrated power supply 230V AC.

Make: SCHNEIDER

Typ: iCM-F-0

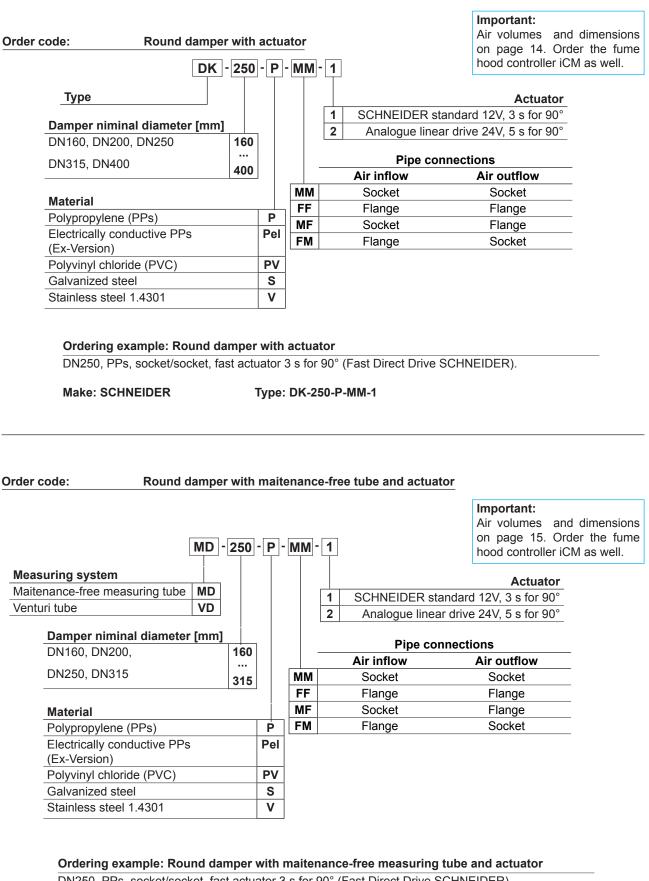
Please order round damper with measuring tube MD or VD and actuator additionally.

### Power supply:

The add-on devices -E1 and -E2 include their own 230V AC power supply. The plug-in power supply is not required for these models and is not included in the scope of delivery.



### Ordering code: Round damper with optional measuring tube



DN250, PPs, socket/socket, fast actuator 3 s for 90° (Fast Direct Drive SCHNEIDER).

#### Make: SCHNEIDER

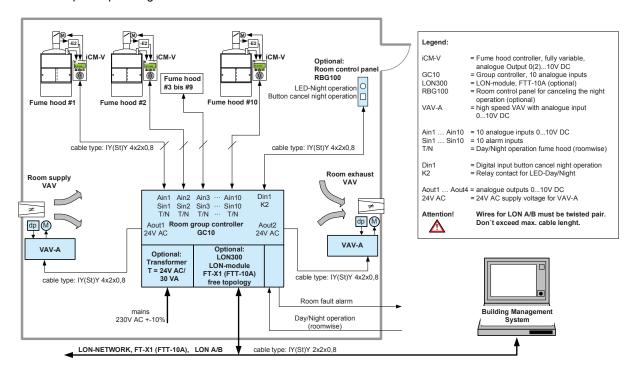
Type: MD-250-P-MM-1

### iCM Fume hood controller

### Room plan 1 • Fume hood controller iCM with analogue output and room group controller GC10

Room plan 1 shows the interconnection of up to 10 fume hood controllers iCM-V (fully variable) and add on system -E2 (Ain1 to Ain10) with the group controller GC10. The group controller can operate up to four freely configurable VAV variable air volume controllers for room supply/exhaust air (Aout1 to Aout4). The internal transformer (optional) provides the supply voltage for the VAV controllers 24V AC, which simplifies planning and reduces construction costs. The analogue inputs Ain1 to Ain10 are summated and can be combined in any number of groups on the analogue outputs Aout1 to Aout4. Optionally, a room by room LON connection to the building services management system is also possible.

For a detailed description see the data sheet GC10.

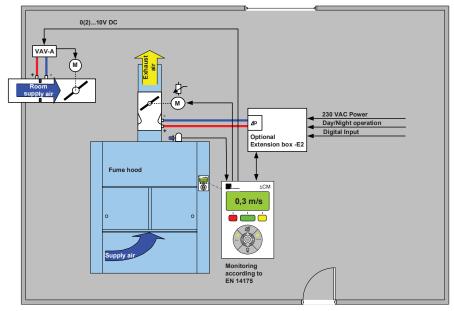


Room plan 2 • Fume hood controller iCM with analogue output and direct actuation of the room VAV

## Direct actuation of the room supply air controller (VAV)

In laboratory applications with a fume hood in the room, the iCM-FP fume hood controller can actuate the room supply air controller directly with 0(2)...10V DC, i.e. room pressure management (e.g. negative pressure in the laboratory) is taken into account for all operating modes of the fume hood.

The optional add on system -E2 provides the 24V AC supply voltage for the room supply air controller. The direct actuation of the room supply air controller means that room pressure management can be achieved cost-effectively.

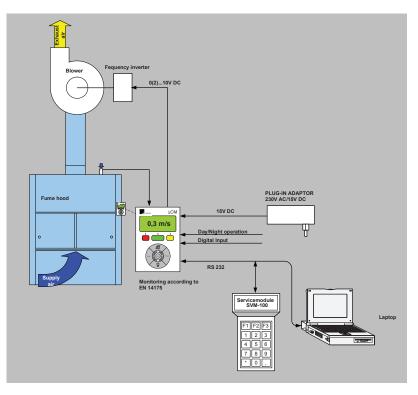




### Direct actuation of the frequency inverter

The analogue output of the iCM-F controller serves as a direct setpoint for the frequency inverter and actuates the exhaust air fan in accordance with the constant face velocity that is to be regulated.

This application is used when the exhaust air fan extracts the air from the fume hood directly.



### Pipe-in-pipe controller

If higher volume flows are required, such as in walk-in hoods, and an even air distribution is desired, this can be achieved by the use of a pipe-in-pipe system.

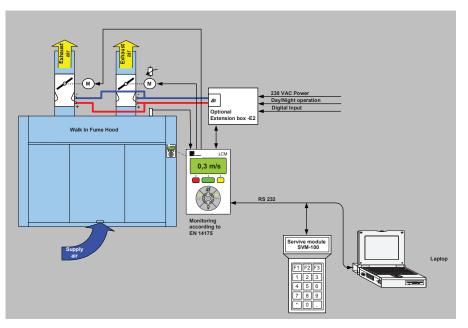
The iCM fume hood controller can actuate up to two venturi measuring tubes with damper. The servo motors are actuated in parallel, ensuring an even distribution of air over both volume flow controllers.

The volume flow actual value is determined via both venturi measuring tubes. The shield factor to be programmed is multiplied by 2.

### Calculation example:

Given: Shield factor B at DN250 = 94

Shield factor in pipe-in-pipe applications: B•2 = 94•2 = 188



### **iCM** Fume hood controller

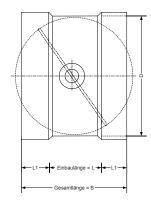


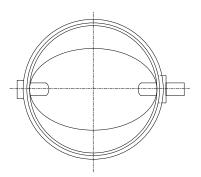
### Damper without measuring tube, PPs (polypropylene, flame resistent), round model, with servo motor

- Control unit: -F (face velocity)
- Fast, stable volume flow control (< 2 s)</p>
- High control accuracy and response sensitivity
- Option: tightly closing damper in accordance with DIN

Nominal diameter	Inner- Ø	Volume flow V <sub>MIN</sub> , V <sub>MAX</sub> , V <sub>NENN</sub> at airflow velociy v				
NW [mm]	D [mm]	v=ca. 0,5 m/s V <sub>MIN</sub> [m³/h]	v=6 m/s V <sub>MAX</sub> [m³/h]	v=ca. 10m/s V <sub>NENN</sub> [m³/h]		
160	161	30	434	589		
200	201	50	679	1005		
250	251	80	1060	1628		
315	316	130	1683	2667		
400	401	217	2714	4347		

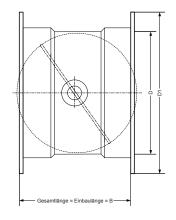
### Model: DK-XXX-P-MM-1 (Muffe/Muffe)

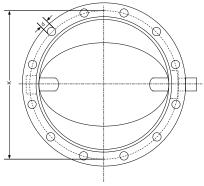




Nominal dia- meter	Inner- Ø		mensio ket/soc	
NW [mm]	D [mm]	B [mm]	L₁ [mm]	L [mm]
160	161	150	40	70
200	201	170	50	70
250	251	175	50	75
315	316	175	50	75
400	401	180	50	80

### Model: DK-XXX-P-FF-1 (Flansch/Flansch)





Nominal dia- meter	Inner- Ø			ensions e/flange	•	
NW [mm]	D [mm]	B [mm]	Outer- Ø D1 [mm]	K [mm]	d [mm]	No
160	161	210	230	200	7	8
200	201	230	270	240	7	8
250	251	235	320	290	7	12
315	316	240	395	350	9	12
400	401	240	480	445	9	16



### iCM Fume hood controller

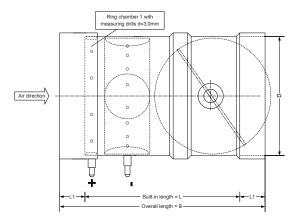
### Dimensions Volume flow ranges

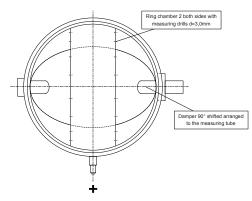
### Maintenance-free measuring tube with damper and servo motor, PPs (polypropylene, flame resistent), round model

- Control unit: analogue, LON, LON balancing
- Fast, stable volume flow control (< 2 s)</li>
- High control accuracy and response sensitivity
- Static differential pressure transmitter 3...300 pa
- Measuring system with integrated ring chamber
- Option: tightly closing damper in accordance with DIN

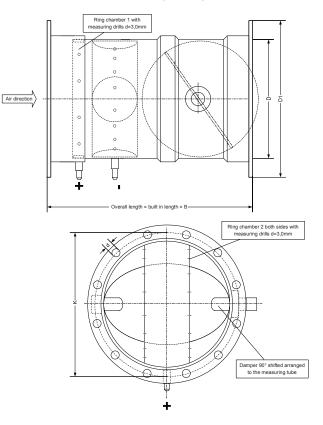
Nominal dia- meter	Inner- Ø	Volume at a	flow V <sub>MIN</sub> , V irflow veloc	<sub>MAX</sub> , V <sub>NOM</sub> ity v		Length	Dimension flange							
NW [mm]	D [mm]	v ≈ 1 m/s V <sub>MIN</sub> [m³/h]	v = 6 m/s V <sub>MAX</sub> [m³/h]	v ≈ 10m/s V <sub>NOM</sub> [m³/h]	L [mm]	L₁ [mm]	B [mm]	Outer- Ø D1 [mm]	K [mm]	d [mm]	No.			
160	161	59	434	589	340	40	260	230	200	7	8			
200	201	100	679	1005	350	50	250	270	240	7	8			
250	251	163	1060	1628	400	50	300	320	290	7	12			
315	316	267	1683	2667	490	50	390	395	350	9	12			

### Model: MD-XXX-P-MM-1 (socket/socket)





### Model: MD-XXX-P-FF-1 (flange/flange)



### Planning notes for determining volume flow:

Bear in mind the volume flow in relation to airflow velocity v

- $V_{MIN}$  = volume flow at airflow velocity v  $\approx$  1 m/s
- $V_{MAX}$  = volume flow at airflow velocity v = 6 m/s (recommended)
- $V_{NOM}$  = volume flow at airflow velocity v  $\approx$  10 m/s

For laboratory applications (exhaust and supply air) the airflow velocity v = 6 m/s at  $V_{MAX}$  should not be exceeded due to the sound levels. If this value is exceeded the sound pressure level of < 52 dB(A) stipulated by DIN1946, Part 7 can only be achieved with very extensive sound absorption. The maximum volume flow  $V_{MAX}$  that is to be regulated should therefore always be less than app. 40% below  $V_{NOM}$ .



### Sound values • Damper with venturi measuring, PPs, round model

### Table 3: Flow noise

mm				∆p <sub>g</sub> = 100 pa												Δ	p <sub>g</sub> = :	250 p	a			∆p <sub>g</sub> = 500 pa										
i u					Lw	in di	B/octa	ave							Lw	in dE	B/octa	ive					L <sub>W</sub> in dB/octave									
feri						f <sub>m</sub> ii	n Hz									f <sub>m</sub> ii	n Hz									f <sub>m</sub> ir	n Hz					
Nominal diameter	v in m/s	V in m³/h	63 HZ	125 Hz	250 Hz	500 Hz	1000 Hz	2000 Hz	4000 Hz	8000 Hz	L <sub>WA</sub> in dB(A)	L in dB(A)	63 HZ	125 Hz	250 Hz	500 Hz	1000 Hz	2000 Hz	4000 Hz	8000 Hz	L <sub>WA</sub> in dB(A)	L in dB(A)	63 HZ	125 Hz	250 Hz	500 Hz	1000 Hz	2000 Hz	4000 Hz	8000 Hz	L <sub>WA</sub> in dB(A)	L in dB(A)
	2	148	50	47	44	46	45	46	33	22	50	42	53	54	53	53	51	50	56	42	60	52	56	58	55	60	59	57	58	54	65	57
	4	290	55	51	48	51	47	42	35	27	52	44	64	61	58	57	55	53	49	43	60	52	67	67	64	63	60	58	60	58	67	59
160	6	434	62	58	53	56	50	46	41	35	56	48	67	65	61	61	58	54	50	45	63	55	72	72	69	67	63	60	59	57	69	61
	8	579	62	60	57	59	55	51	49	45	61	53	71	67	64	64	60	56	53	48	66	58	75	73	71	69	65	62	59	56	71	63
$\vdash$	10	724	67	66	62	58	59	55	54	51	64	56	73	70	66	68	62	59	55	51	69	61	76	76	72	72	67	64	61	58	73	65
	2	226	47	50	47	47	47	46	49 56	39 42	54 63	46 55	50	53 62	52	56	57	58	57	59	65 67	57	55	57	54	59	63	67	67	66 66	73 73	65
200	4	452 679	56 59	57 61	53 56	51 55	53 58	60 58	50	42	63	55	59 65	62 66	60 64	60 63	59 63	59 63	60 63	62 64	70	59 62	61 68	64 70	64 70	66 70	66 69	67 69	66 67	70	76	65 68
200	8	905	61	64	60	57	59	58	52	46	64	56	69	72	67	66	67	68	66	61	73	65	70	74	72	73	72	71	69	69	78	70
	10	1131	63	65	62	59	62	60	55	50	66	58	74	72	70	68	69	69	65	61	75	67	75	77	74	74	74	73	71	70	80	72
	2	353	50	47	44	46	45	46	33	22	50	42	53	54	53	53	51	50	56	42	60	52	56	58	55	60	59	57	58	54	65	57
	4	707	55	51	48	51	47	42	35	27	52	44	64	61	58	57	55	53	49	43	60	52	67	67	64	63	60	58	60	58	67	59
250	6	1060	62	58	53	56	50	46	41	35	56	48	67	65	61	61	58	54	50	45	63	55	72	72	69	67	63	60	59	57	69	61
	8	1414	62	60	57	59	55	51	49	45	61	53	71	67	64	64	60	56	53	48	66	58	75	73	71	69	65	62	59	56	71	63
	10	1767	67	66	62	58	59	55	54	51	64	56	73	70	66	68	62	59	55	51	69	61	76	76	72	72	67	64	61	58	73	65
	2	561	42	47	45	43	38	35	33	32	45	37	47	47	49	51	54	52	50	50	57	49	52	52	54	56	59	57	55	55	62	54
	4	1122	52	55	50	49	43	38	31	29	50	42	60	61	57	55	55	51	47	48	59	51	65	66	62	60	60	56	52	53	64	56
315	6	1683	54	57	52	51	45	40	33	31	52	44	62	63	59	57	57	53	49	50	61	53	67	68	64	62	62	58	54	55	66	58
	8	2244	59	57	56	55	47	43	38	33	55	47	67	68	64	61	58	55	51	50	64	58	72	73	69	66	63	60	56	55	69	61
	10	2806	61	59	58	57	49	45	40	35	57	49	69	70	66	63	60	57	53	52	66	58	74	75	71	68	65	62	58	57	71	63
	2	905	41	48	47	44	38	36	34	32	46	38	48	49	49	50	53	50	48	48	57	49	53	54	54	55	58	55	53	53	62	54
400	4	1810 2714	53 55	54 56	53 55	52 54	46 48	40 42	34 36	30 32	52 54	44	62 64	62 64	59 61	57	54 56	52 54	48 50	47 49	60 62	52 54	67 69	67 69	64	62 64	59 61	57 59	53 55	52 54	65 67	57
400	6 8	3619	55 60	56 58	55 61	54 62	48 53	42	36 42	32 35	54 61	46 53	64 66	64 68	67	59 64	56 59	54 56	50 51	49 50	62 66	54 58	69 73	69 73	66 72	64 69	64	59 61	55 56	54 55	67 71	59 63
	0 10	4524	62	56 60	63	62 64	55	40 48	42	35 37	63	55	70	00 70	67 69	66	59 61	58	53	50 52	68	50 60	75	75	74	69 71	66	63	50 58	55 57	73	65
	10	4524	02	00	05	04	55	40	44	51	05	55	10	10	09	00	01	50	55	JZ	00	00	15	15	/4	11	00	05	50	51	15	00

Definitions:		
f <sub>m</sub>	in Hz:	Centre frequency of the octavos
Lw	in dB/octave:	Sound power level measured in the echo chamber
L <sub>WA</sub>	in dB(A):	Total sound power level, A-weighted
L	in dB(A):	Sound pressure level, A-weighted, room insulation of 8dB/octave taken into ac- count
$\Delta p_g$	in Pa:	Total pressure difference (measured in front of and behind the volume flow control- ler)
V	in m3/h:	Volume flow
V	in m/s:	Flow velocity

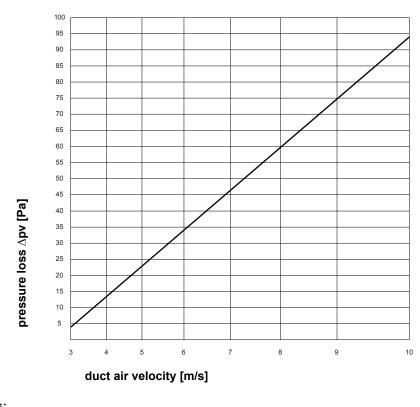


### Sound values • Damper with venturi measuring, PPs, round model

### Table 4: Sound emission

				∆p <sub>g</sub> = 100 pa												Δ	pg =	250 p	а							Δ	pg =	500 p	a			
u m					Lw	in de	B/octa	ave					L <sub>W</sub> in dB/octave									L <sub>w</sub> in dB/octave										
						f <sub>m</sub> i	n Hz						f <sub>m</sub> in Hz fr									f <sub>m</sub> ii	n Hz									
Nominal diameter in	v in m/s	V in m³/h	63 HZ	125 Hz	250 Hz	500 Hz	1000 Hz	2000 Hz	4000 Hz	8000 Hz	L <sub>WA</sub> in dB(A)	L in dB(A)	63 HZ	125 Hz	250 Hz	500 Hz	1000 Hz	2000 Hz	4000 Hz	8000 Hz	L <sub>WA</sub> in dB(A)	L in dB(A)	63 HZ	125 Hz	250 Hz	500 Hz	1000 Hz	2000 Hz	4000 Hz	8000 Hz	L <sub>WA</sub> in dB(A)	L in dB(A)
	2	148	30	28	21	20	26	28	15	9	31	23	33	26	24	25	36	38	31	20	42	34	33	25	26	31	42	47	41	33	50	42
	4	290	38	32	27	23	27	27	20	7	32	24	43	36	32	29	36	38	30	22	41	33	42	37	36	34	42	45	39	32	49	41
160	6	434	41	34	32	29	30	29	22	9	35	27	47	41	38	33	37	38	33	23	43	35	48	44	42	38	44	46	40	33	49	41
	8	579	46	41	40	39	35	31	22	10	41	33	49	43	42	38	40	40	35	26	45	37	54	48	47	41	46	47	41	34	51	43
	10	724	51	45	46	46	41	37	28	18	47	39	52	46	45	42	43	42	36	26	48	40	54	50	49	44	47	48	43	35	53	45
	2	226	24	22	20	19	20	20	20	6	26	18	28	30	27	27	26	28	27	22	34	26	37	31	28	32	34	37	32	33	41	33
200	4	452	31	33	27	23	23 28	27 28	20	6	31	23	38	37	33 38	30	30	30	29	29	37	29	53	39	37	42	39	38	34 35	34	45	37
200	8	679 905	38 39	37 39	32 35	28 33	20 33	20 30	20 22	12 14	33 37	25 29	44	43 44	30 41	34 39	33 38	35 38	31 32	29 26	40 43	32 35	47 47	46 47	42 46	44 45	41 44	40 43	35 41	34 37	47 50	39 42
	10	1131	43	43	39	37	38	33	26	14	41	33	52	44	41	41	40	40	34	30	43	38	54	52	40	43	44	43	41	38	51	42
	2	353	30	28	21	20	26	28	15	9	31	23	33	26	24	25	36	38	31	20	42	34	33	25	26	31	42	47	41	33	50	42
	4	707	38	32	27	23	27	27	20	7	32	24	43	36	32	29	36	38	30	22	41	33	42	37	36	34	42	45	39	32	49	41
250	6	1060	41	34	32	29	30	29	22	9	35	27	47	41	38	33	37	38	33	23	43	35	48	44	42	38	44	46	40	33	49	41
	8	1414	46	41	40	39	35	31	22	10	41	33	49	43	42	38	40	40	35	26	45	37	54	48	47	41	46	47	41	34	51	43
	10	1767	51	45	46	46	41	37	28	18	47	39	52	46	45	42	43	42	36	26	48	40	54	50	49	44	47	48	43	35	53	45
	2	561	34	34	31	29	25	24	24	24	33	25	39	34	35	37	41	41	41	42	45	37	44	39	40	42	46	46	46	47	50	42
	4	1122	44	42	36	35	30	27	22	21	38	30	52	48	43	41	42	40	38	40	47	39	57	53	48	46	47	45	43	45	52	44
315	6	1683	46	44	38	37	32	29	24	23	40	32	54	50	45	43	44	42	40	42	49	41	59	55	50	48	49	47	45	47	54	46
	8	2244	51	44	42	41	34	32	29	25	43	35	59	55	50	47	45	44	42	42	52	44	64	60	55	52	50	49	47	47	57	49
	10	2806	53	46	44	43	36	34	31	27	45	37	61	57	52	49	47	46	44	44	54	46	66	62	57	54	52	51	49	49	59	51
	2	905	33	36	33	33	25	26	26	24	34	26	40	37	35	35	40	40	40	40	45	37	45	42	40	40	45	45	45	45	50	42
	4	1810	45	42	39	39	33	30	26	22	40	32	54	50	45	45	41	42	40	39	48	40	59	55	50	50	46	47	45	44	53	45
400	6	2714	47	44	41	41	35	32	28	24	42	34	56	52	47	47	43	44	42	41	50	42	61	57	52	52	48	49	47	46	55	47
	8	3619	52	46	47	47	40	36	34	27	49	41	60	56	53	53	46	46	43	42	54	46	65	61	58	58	51	51	48	47	59	51
	10	4524	54	48	49	49	42	38	36	29	51	43	62	58	55	55	48	48	45	44	56	48	67	63	60	60	53	53	50	49	61	53

### Pressure loss table • Damper with venturi measuring, PPs, round model



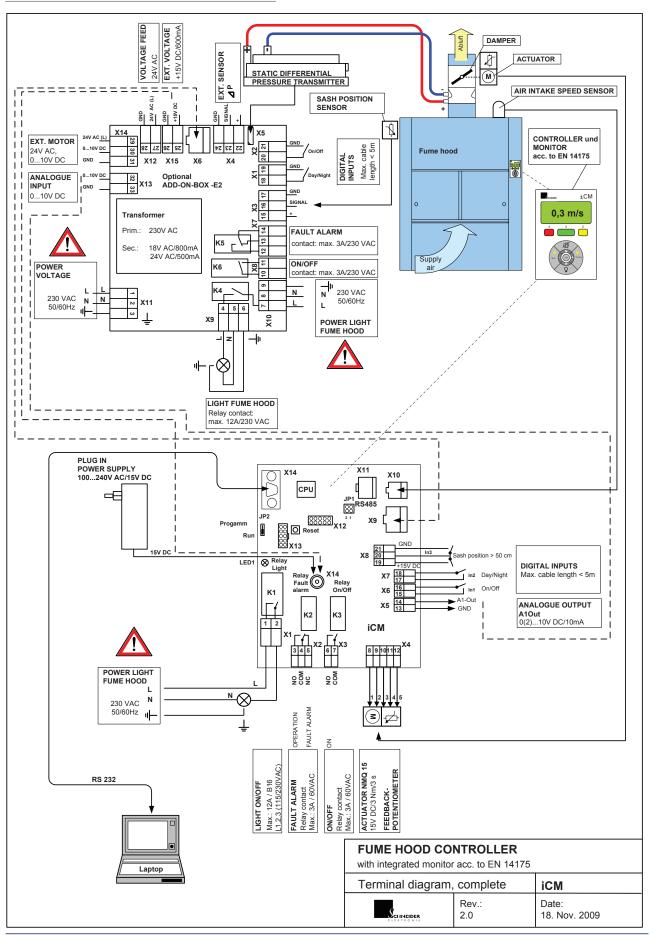
### Table 5: Pressure loss

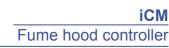
### **Definitions:**

in Pa: Total pressure loss with fully open damper (measured in front of and behind the volume flow controller)

Terminal diagram

### Terminal diagram: Fume hood controller iCM





### **Technical data**

Standard model iCM-F (face velocity)							
General							
Plug in power supply	230/110V AC/50/60Hz/ +-15%						
Max. current	100 mA						
Max. power input	20 VA						
Reactivation time	600ms						
Operating temperature	0 °C to +55 °C						
Humidity	max. 80 % relative, non- condensing						

Case (iCM controller)	
Protection type	IP 20
Material	plastic
Colour	grey
Dimensions (LxWxH)	(134 x 80 x 40) mm
Weight	approx. 1,0 kg
Terminals	screw terminal 0,75 mm <sup>2</sup>

Relay outputs	
Number	1 relay (K1)
Contact type	front contact
Max. switching voltage	250V AC
Max. continuous current	3A
Number	2 relays (K2, K3)
Contact type	changeover/ front contact
Max. switching voltage	250V AC
Max. continuous current	2A

### Digital inputs

2 inputs

5V DC, 5mA

Analogue output

1 output

0(2)...10VDC, 10mA

Air flow sensor AFS100									
Measuring principle	dynamic, heat wire								
	anemometric principle								
Flow range	01 m/s								
Response time	< 100 ms								

Damper without venturi measuring tube									
Number	4 optocouplers								
Max. input voltage	24V DC +-15%								
Max. continuous current	10mA (per input)								

Servo motor	
Torque	3 Nm
Running time	3 sec. for 90 degrees
Activation	directly drive with integrated current monitor
Resolution	< 0,5°
Angle feedback	< 0,5° via potentiometer

#### Extended operating mode wit add on system -E2 General Internal power supply 230/110V AC/50/60Hz/ +-15% Max. current 100 mA Max. power input 20 VA **Reactivation time** 600ms **Operating temperature** 0 °C to +55 °C Humidity max. 80 % relative, noncondensing

Case (add on system)	
Protection type	IP 20
Material	sheet steel
Colour	white, RAL 9002
Dimensions (LxWxH)	(185 x 167 x 92) mm
Weight	approx. 1,5 kg
Terminals	screw terminal 1.5 mm <sup>2</sup>

### Sash position sensor SPS100

Measuring principle	static, cable pull potentiometer
Measuring range	01000 mm
Accuracy	± 2 mm
Response time	< 1 ms

### Differential pressure transmitter

static
3300 pascal
8800 pascal optional
< 0,1 %
< 10 ms
500 mbar

Relay outputs	
Number	1 relay (K1)
Contact type	front contact
Max. switching voltage	250V AC
Max. continuous current	16A
Number	2 relays (K2, K3)
Contact type	changeover contact
Max. switching voltage	250V AC
Max. continuous current	12A

### Analogue input

1 input

0(2)...10VDC, 1mA

<ul> <li>Digital inputs (galvanically separated)</li> </ul>	
Number	2 optocouplers
Max. input voltage	24V DC +-15%
Max. continuous current	10mA (per input)

Maintenance-free measuring tube with damper	
Material	polypropylene (PPs)
Measuring system	maintenance-free measu- ring tube with two ring chambers, optionally venturi tube

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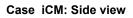
0.3 m/s

iСМ

### Dimensions • Dimensional diagrams • Tender specification

### Case iCM: Top view

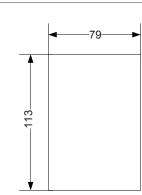
38



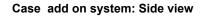
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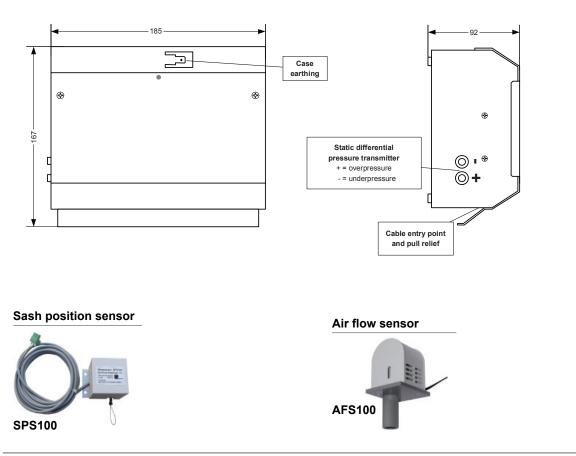
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Case add on system: top view





### Tender specification iCM-F

Fume hood controller with integrated microprocessor, independent watchdog circuit and air flow sensor. Variable fume hood control depending on the sash position (constant face velocity freely programmable) with integrated safe operation monitoring function in accordance with EN 14175 with acoustic and optical alarm. Optical and optionally acoustic alarm for the operating status "Sash position > 50cm". Full graphic LC display with numerical display of the face velocity in m/s or ft/min. System data storage in mains voltage failure-safe EEPROM. Controller in compact built in case with separate air flow sensor. Direct digitalisation of the high speed actuator (< 3 s for 90°) for precise and stable control without any fluctuations. Damper model in PPs. All cables are ready to plug in. With optional add-on system upgradeable for extended operating modes. Suitable for all fume hood constructions.

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